

# **SR2\_Analog\_810\_mk1**

## **User's Manual**

by



with the collaboration of



January 16 2012



<b>1</b>	<b>INTRODUCTION</b>	<b>5</b>
<b>2</b>	<b>TECHNICAL DATA</b>	<b>5</b>
2.1	Sampling Frequency (TCXO)	5
2.2	Analog Inputs	5
2.3	Analog Outputs	6
2.4	General-Purpose IOs	6
2.5	Counters	6
<b>3</b>	<b>CONNECTOR PINOUTS</b>	<b>7</b>
3.1.1	ADC Connector Pinouts	7
3.1.2	DAC Connector Pinouts	8
3.1.3	Auxiliary +-12 V Power Supplies	9
3.1.4	GPIO and Counters Connector Pinout	9
<b>4</b>	<b>INSTALLATION</b>	<b>10</b>
4.1	Software Installation	10
4.2	Development Resources	10
4.3	FPGA Configuration	10
4.4	Mating to the DSP board	10
<b>5</b>	<b>FPGA LOGIC</b>	<b>11</b>
5.1	Registers	11
5.2	Control Register	12
5.3	ADC and DAC Operation	12
5.3.1	Period Register	13
5.4	Counter Operation	13
5.4.1	Pins and Functions	13
5.4.2	Counter Management	14
5.5	General-Purpose and Counter Inputs and Outputs	14
5.5.1	GPIO Registers	14
5.6	Reset and Sequencing	15
5.6.1	Sequencing	15
5.6.2	Start Sequence	15

<b>5.7</b>	<b>Bus Switches</b>	<b>15</b>
<b>6</b>	<b>SOFTWARE</b>	<b>16</b>
<b>6.1</b>	<b>Demo Applications</b>	<b>16</b>
6.1.1	Time Signal Tab	17
6.1.2	Sxx Tab	17
6.1.3	Acquisition Set-Up Tab	18
6.1.4	Digital IOs Tab	20
6.1.5	Board/FPGA Info Tab	21
<b>6.2</b>	<b>SR2_Analog_810 Drivers and Example Codes</b>	<b>22</b>
6.2.1	Overview	22
6.2.2	FPGA Logic	22
6.2.3	User-Accessible Structures and Functions	22
6.2.4	Used Resources	25
6.2.5	Restrictions	25
6.2.6	Driver Lock-Up <i>SR2_NG Only</i>	26

## 1 Introduction

*SR2\_Analog\_810\_mk1* is the second generation of the *SR2\_Analog\_810* data acquisition board. Compared with the earlier generation it offers the following improvements:

- Analog filters on the outputs to minimize the visibility of the DAC glitches
- The sampling frequency is stabilized by a TCXO for high-stability applications

*Note: The DSP board's FPGA is used to manage the ADCs and DACs on SR2\_Analog\_810\_mk1. To be functional the FPGA must be loaded with a special logic that is different from the factory-default logic. Any logic implemented in the FPGA of the DSP board at power-up that is not the logic designed for SR2\_Analog\_810 or SR2\_Analog\_810\_mk1, including the factory-default logic, has the potential to damage the FPGA and the SR2\_Analog\_810\_mk1 board. If SR2\_Analog\_810\_mk1 has been purchased separately from the DSP board we recommend to either load the appropriate FPGA logic, or erase any logic from Flash prior to mating SR2\_Analog\_810\_mk1 to the DSP board. The procedure for erasing the Flash is described in the DSP board's user manual.*

*Note: The TCXO function of SR2\_Analog\_810\_mk1 is only supported on the following DSP boards: Signal\_Ranger\_mk2\_NG, Signal\_Ranger\_mk3. The companion software does not support Signal\_Ranger\_mk2.*

*However, the SR2\_Analog\_810\_mk1 board is compatible with the SR2\_Analog\_810 board and its FPGA logic. If the TCXO function is not needed, the newer SR2\_Analog\_810\_mk1 board can be swapped for the earlier SR2\_Analog\_810 board. Earlier DSP software and FPGA logic will work on SR2\_Analog\_810\_mk1.*

*Note: To support the TCXO function, the FPGA must be loaded with the new file SR2\_Analog\_810\_TCXO\_V200.rbt. The old logic named SR2\_Analog\_810\_V200.rbt will work, but will use the standard clock reference, rather than the TCXO. So if the TCXO is not required, the new SR2\_Analog\_810\_mk1 board is compatible and can be swapped for an older SR2\_Analog\_810.*

## 2 Technical Data

### 2.1 Sampling Frequency (TCXO)

- Precision: 2 ppm
- Stability: 140 ppb over temperature range (-20 degC to 70 degC)

### 2.2 Analog Inputs

- Number of inputs: 8
- Resolution: 16 bits
- Noise: 1 bit RMS (= 150  $\mu$ V RMS on +-5V range)  
1 bit RMS (= 300  $\mu$ V RMS on +-10V range)
- Sampling rate: 11.4 Hz to 150kHz
- Analog input bandwidth: 0 to 10 MHz (includes DC)
- Input type: Single Ended
- Dynamic ranges: +-5V, +-10V

- Input leakage:  $\pm 1 \mu\text{A}$  max
- Anti-aliasing filter: None
- Group-delay: 2 samples (includes all hardware and software FIFO delay)

### 2.3 Analog Outputs

- Number of outputs: 8
- Resolution: 16 bits
- Noise:
  - 20MHz bandwidth:  $< 500 \mu\text{V}$  RMS on stable output code.
  - 20 kHz bandwidth:  $< 25 \mu\text{V}$  RMS on stable output code
- Glitch:
  - 20MHz bandwidth:  $< 6 \text{ mVpk}$  on  $\text{FFFF}_\text{H}$ - $0000_\text{H}$  (worst-case) code change.
  - 20 kHz bandwidth:  $< 1 \text{ mVpk}$  on  $\text{FFFF}_\text{H}$ - $0000_\text{H}$  (worst-case) code change.
- Offset drift with temperature:  $\pm 2 \text{ ppm FSR} / \text{degC}$
- Gain drift with temperature:  $\pm 2 \text{ ppm FSR} / \text{degC}$
- Offset drift with time:  $\pm 13 \text{ ppm FSR} / 500 \text{ hours}$
- Sampling rate: 11.4 Hz to 150kHz
- Analog output bandwidth: 0 to  $>75 \text{ kHz}$  (includes DC)
- Output type: Single Ended
- Dynamic range:  $\pm 10\text{V}$
- Source/Sink ability: 25 mA
- Anti-aliasing filter: 2-pole 75 kHz cutoff
- Group-delay: (includes all hardware and software FIFO delay)
  - *Out\_0* and *Out\_1*: 2.5 samples
  - *Out\_2* and *Out\_3*: 2.75 samples
  - *Out\_4* and *Out\_5*: 3 samples
  - *Out\_6* and *Out\_7*: 3.25 samples

### 2.4 General-Purpose IOs

- Number of IOs: 16
- Configurability: All IOs individually configurable as input or output.
- IO level: 3.3V CMOS (5V-tolerant inputs)

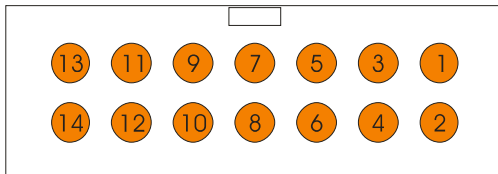
### 2.5 Counters

- Number of counters: 2
- Counter width: 16-bits (can be increased to any width in software).
- Inputs: Two quadrature encoder inputs *QEP\_A* and *QEP\_B*, and a general-purpose *Pulse* input per counter.
- IO level: 3.3V CMOS (5V-tolerant inputs)
- Max count frequency: 50 MHz
- Min pulse width: 20 ns (to be reliably counted the high and low states on the counter inputs must be at least 20ns wide).
- Synchronism: Both counters are sampled synchronously to the ADC samples.

## 3 Connector Pinouts

*Note: All connectors below are represented with the ADC and DAC connectors facing up, the J3 connector to the left and the J6 connector facing down.*

### 3.1.1 ADC Connector Pinouts



**Figure 1 J1 – J2 connector pinouts**

#### 3.1.1.1 J1

No	Function	No	Function
1	-12V	2	+12V
3	Gnd	4	ADC_11 (not managed)
5	Gnd	6	ADC_9 (not managed)
7	Gnd	8	ADC_7
9	Gnd	10	ADC_5
11	Gnd	12	ADC_3
13	Gnd	14	ADC_1

**Table 1 Connector J1**

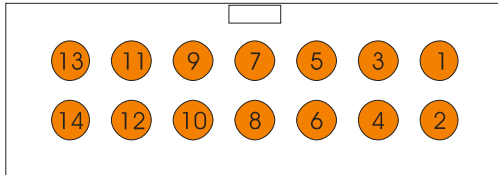
#### 3.1.1.2 J2

No	Function	No	Function
1	-12V	2	+12V
3	Gnd	4	ADC_10 (not managed)
5	Gnd	6	ADC_8 (not managed)
7	Gnd	8	ADC_6
9	Gnd	10	ADC_4
11	Gnd	12	ADC_2

13	Gnd	14	ADC_0
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**Table 2 Connector J2**

### 3.1.2 DAC Connector Pinouts



**Figure 2 J4 – J5 connector pinouts**

#### 3.1.2.1 J4

No	Function	No	Function
1	-12V	2	+12V
3	Gnd	4	Gnd
5	Gnd	6	Gnd
7	Gnd	8	DAC_6
9	Gnd	10	DAC_4
11	Gnd	12	DAC_2
13	Gnd	14	DAC_0

**Table 3 Connector J4**

#### 3.1.2.2 J5

No	Function	No	Function
1	-12V	2	+12V
3	Gnd	4	Gnd
5	Gnd	6	Gnd
7	Gnd	8	DAC_7
9	Gnd	10	DAC_5
11	Gnd	12	DAC_3
13	Gnd	14	DAC_1

**Table 4 Connector J5**

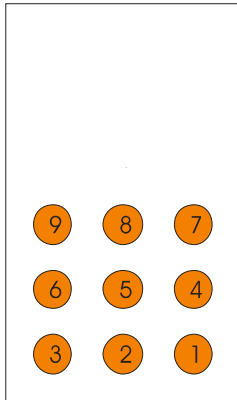


## 3.1.3 Auxiliary +-12 V Power Supplies

The J1, J2, J3 and J4 connectors provide auxiliary +12 V and -12 V taps that can be used to power external user circuitry. When using these taps the following precautions must be taken:

- The total current drawn from all the +12 V taps must not be greater than 100 mA. The limit is not 100mA per tap, but 100 mA for all taps.
- The total current drawn from all the -12 V taps must not be greater than 100 mA. The limit is not 100mA per tap, but 100 mA for all taps.
- Drawing current from these taps increases the power-supply noise up to 13mV pk-pk for 100 mA.

## 3.1.4 GPIO and Counters Connector Pinout



**Figure 3 J3 connector pinout**

No	Function	No	Function	No	Function
36	GPIO_0(0)	35	Gnd	34	GPIO_0(1)
33	GPIO_0(2)	32	Gnd	31	GPIO_0(3)
30	GPIO_0(4)	29	Gnd	28	GPIO_0(5)
27	GPIO_0(6)	26	Gnd	25	GPIO_0(7)
24	GPIO_0(8)	23	Gnd	22	GPIO_0(9)
21	GPIO_0(10)	20	Gnd	19	GPIO_0(11)
18	GPIO_0(12)	17	Gnd	16	GPIO_0(13)
15	GPIO_0(14)	14	Gnd	13	GPIO_0(15)
12	Pulse_0	11	Gnd	10	Pulse_1
9	QEP_A_0	8	Gnd	7	QEP_A_1
6	QEP_B_0	5	Gnd	4	QEP_B_1

3	NC	2	Gnd	1	Presence
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**Table 5 J3 connector pinout**

*Note: The Presence pin must be grounded for the GPIO pins to be connected to the FPGA through the bus switches. When experimenting directly on the connector a simple jumper to ground may be used.*

## 4 Installation

### 4.1 Software Installation

Unzip the *SR3\_Applications\_Installer\_Vxxx.zip* file and run *setup.exe*. This installs the following:

- A directory *SR3\_Applications* in *C:\Program Files* (if it did not exist already) containing documentation, LabVIEW libraries, Test applications, DSP code examples...etc.
- Shortcuts to compiled test applications and documentation.

### 4.2 Development Resources

LabVIEW developers can find all the relevant resources in the following distribution: *SR3\_DDCI\_Library\_Distribution\_Vxxx.zip*. Those development resources include Vis and DSP code that are specific to the *SR2\_Analog\_810* IO board. See the *SignalRanger\_mk3\_Pro\_UsersManual* for more information about those development resources.

### 4.3 FPGA Configuration

The FPGA on the DSP board is used to manage the ADCs and DACs on *SR2\_Analog\_810\_mk1*. To be functional the FPGA must be loaded with a special logic *SR2\_Analog\_810\_TCXO\_V200.rbt* that is different from the factory-default logic implemented on the DSP board, and is different from the logic designed for the standard *SR2\_Analog\_810* board.

*Note: The FPGA logic SR2\_Analog\_810\_V200.rbt designed for the earlier SR2\_Analog\_810 board will work on the SR2\_Analog\_810\_mk1 board. However it will not use the TCXO. It will use the standard oscillator instead, which is not as stable.*

The demo applications that are provided with the board load the FPGA dynamically. They do not need any FPGA configuration to be pre-loaded in Flash ROM.

However any logic present in the Flash ROM of the DSP board will be implemented at power-up. If it is different from the logic designed for *SR2\_Analog\_810\_mk1* (including the DSP board's factory-default logic) it has the potential to damage the FPGA and the *SR2\_Analog\_810\_mk1* board. If *SR2\_Analog\_810\_mk1* has been purchased separately from the DSP board we recommend to either remove any logic from the Flash of the DSP board, or load the *SR2\_Analog\_810\_TCXO\_V200.rbt* logic in Flash prior to mating *SR2\_Analog\_810\_mk1* to the DSP board. Procedures for erasing and programming the Flash are described in the DSP board's user manual.

### 4.4 Mating to the DSP board

When *SR2\_Analog\_810\_mk1* is purchased with a DSP board the two boards are already mated. If not *SR2\_Analog\_810\_mk1* must be mated to the DSP board prior to powering-up. Before mating the two boards make sure that no FPGA logic other than *SR2\_Analog\_810\_TCXO\_V200.rbt* is present in the Flash of the DSP board. Never attempt to mate the two boards while the DSP board is powered.

When *SR2\_Analog\_810\_mk1* is mated to a *Signal\_Ranger\_mk3\_Pro* board a plastic cap is required on the central connector (J7) of the *Signal\_Ranger\_mk3\_Pro* board. The following picture shows the plastic cap.



**Figure 4 Plastic cap on J7**

## 5 FPGA Logic

### 5.1 Registers

All the functions of the FPGA logic are configurable through a set of 7 registers. The registers and their addresses are listed in table 1.

Register	R/W	DSP Byte-Address	Function
Control	R/W	46000000 <sub>H</sub>	Main Control Register
FIFO_Data	R/W	46000002 <sub>H</sub>	ADC and DAC FIFO access
Period	R/W	46000004 <sub>H</sub>	Sampling Period Register
GPIO_0_Data	R/W	46000006 <sub>H</sub>	16-bit parallel port 0
GPIO_0_Dir	R/W	46000008 <sub>H</sub>	Direction port 0
QEP_Count_0_FIFO	R	4600000A <sub>H</sub>	16-bit counter 0 FIFO
QEP_Count_1_FIFO	R	4600000C <sub>H</sub>	16-bit counter 1 FIFO

**Table 6 FPGA registers (SR3\_Pro)**

Register	R/W	DSP Byte-Address	DSP Word-Address	Function
Control	R/W	C00002 <sub>H</sub>	600001 <sub>H</sub>	Main Control Register
FIFO_Data	R/W	C00006 <sub>H</sub>	600003 <sub>H</sub>	ADC and DAC FIFO access
Period	R/W	C0000A <sub>H</sub>	600005 <sub>H</sub>	Sampling Period Register
GPIO_0_Data	R/W	C0000E <sub>H</sub>	600007 <sub>H</sub>	16-bit parallel

				port 0
GPIO_0_Dir	R/W	C00012 <sub>H</sub>	600009 <sub>H</sub>	Direction port 0
QEP_Count_0_FIFO	R	C00016 <sub>H</sub>	60000B <sub>H</sub>	16-bit counter 0 FIFO
QEP_Count_1_FIFO	R	C0001A <sub>H</sub>	60000D <sub>H</sub>	16-bit counter 1 FIFO

**Table 7 FPGA registers (SR2\_NG)**

## 5.2 Control Register

Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Name															ADC_Range	Run
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset state	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

**Table 8 Control register**

Bit	Function
Run	<p>Resetting this bit to 0 performs the following:</p> <ul style="list-style-type: none"> <li>All the FPGA logic is maintained in reset.</li> <li>All ADC and DAC operations are suspended.</li> <li>The RSTIN and CLR DAC signals, as well as the RESET ADC signals are activated, maintaining both ADCs and DACs in reset.</li> </ul> <p>When this bit is set the logic starts operating at the sampling frequency set by <i>Period</i>.</p>
ADC_Range	<p>This bit defines the state of the <i>RANGE</i> signal of the ADC. The range adjustment is as follows:</p> <ul style="list-style-type: none"> <li>1 +5V</li> <li>0 +10V</li> </ul>

**Table 9 Control bits**

## 5.3 ADC and DAC Operation

The *FIFO\_Data* register accesses both the ADC and DAC FIFOs. To fill the DAC FIFO simply write words in succession to the FIFO's address. To read the ADC FIFO simply read words in succession from the same address. Both FIFOs have a depth of 16 words. This is twice the number of samples required for one sampling period.

After reset the DAC FIFO is empty. This way the first words sent by the DSP as soon as the first interrupt is triggered are immediately output to the DACs. This minimizes the group delay of the output chain.

After reset the ADC FIFO contains 8 words at 0. These words must be read by the DSP as soon as the interrupt is triggered. These words represent ADC samples read in the previous sampling period. The first time around there has not been an ADC sampling yet. This is why the ADC FIFO contains 8 samples at zero. At the next interrupt, the ADC FIFO contains the 8 words sampled during the first period (see section *Reset and Sequencing*).

#### 5.3.1 Period Register

The *Period* register adjusts the sampling frequency. The sampling frequency is calculated as:

$$F_s = \frac{Clk - In}{N \times 200} \text{ where } N \text{ is the content of } Period.$$

The sampling frequency cannot be higher than 150 kHz, which corresponds to a *Period* value of 5. Any value between 0 and 5 is forced at 5.

The *Period* register should not be changed while the logic is operating. The proper procedure to change the value is:

- Write 0 to the *Run* bit of the *Control* register to stop and reset the FPGA logic.
- Write the new value to the *Period* register.
- Write 1 to the *Run* bit of the *Control* register to start the FPGA logic.

### 5.4 Counter Operation

#### 5.4.1 Pins and Functions

Each counter has three pins available on the J3 connector:

- Pulse
- QEP\_A
- QEP\_B

The *Pulse* function and the *QEP* function are exclusive. The counter can be used as a pulse counter, or as a *QEP* counter but not both. The presence of transitions on both sets of pins gives unexpected results.

All pins are maintained by keepers. An unused pin can be grounded, or can be left unconnected.

##### 5.4.1.1 Pulse Function

When the counter is used to count pulses the *QEP\_A* and *QEP\_B* inputs should be grounded or left unconnected.

The pulse source is connected to the *Pulse* input. The counter counts rising transitions. The counter can count as many as  $50 \cdot 10^6$  transitions per second. The signal must be stable at 0 or 1 for at least 20ns for the transitions to be reliably counted.

##### 5.4.1.2 QEP Function

When the counter is used to count quadrature encoder transitions the A and B channels of the encoder must be connected to the *QEP\_A* and *QEP\_B* inputs. The *Pulse* input should be grounded or left unconnected.

The counter counts every transition on both channels (x4 decoding). The counter can count as many as  $50 \cdot 10^6$  transitions per second. The signal on both channels must be stable at 0 or 1 for at least 20ns for the transitions to be reliably counted.

### 5.4.2 Counter Management

The counter contents are sampled precisely at the same time as the ADCs and filed into their respective FIFOs. This means that the counter contents are perfectly synchronous to, and have the same latency as the ADC samples.

#### 5.4.2.1 Software Counter Width Extension

The counters are only 16-bit wide, but they can easily be extended to 32 or more bits by software by the following processing:

1. Read the counter FIFO. This represents the contents of the counter as it was sampled during the previous sampling period.
2. Subtract the current reading from the reading at the previous sampling period. Use a subtraction operator that operates on 16-bit two's complement signed numbers without saturating the result (allowing roll-over). The result represents precisely the pulses or transitions that have been counted during the previous sampling period. The timing is extremely precise and unaffected by any software latency because the counter contents are sampled at a precise instant in every sampling period.
3. Add the 16-bit signed result from step two to a larger (32-bit or more) counter.

*Note: To be exact the sampling rate must be high enough, relative to the maximum pulse rate so that the counter cannot count more than 65536 counts in a single sampling period.*

#### 5.4.2.2 Software Gating

To gate the counters in software, modify step 3 above to optionally not add the result of step 2 to the software counter, depending on the state of a gating variable (*true* or *false*).

Because the counters are sampled at a precise instant in every period the resulting software gating window length is a very precise multiple of the number of periods. The precision of the window length is unaffected by any software latency.

### 5.5 General-Purpose and Counter Inputs and Outputs

The board provides 16 general-purpose input-output pins (GPIOs). These pins are accessible on the J3 connector. Each pin can be individually configured as input or output via a direction register.

#### 5.5.1 GPIO Registers

The direction register *GPIO\_Dir\_0* contains bits that configure each pin as input (0) or output (1).

Reading the data register *GPIO\_Data\_0* returns the state of the corresponding port pins, irrespective of its configuration (input or output).

Writing the data register *GPIO\_Data\_0* sets the state of the port pins that are configured as outputs. It has no impact on the port pins that are configured as inputs.

An open drain function can be emulated by writing 0 to the specified bit position of *GPIO\_Data\_0* and controlling the specified bit position of *GPIO\_Dir\_0*.

The register contents are as follows:

Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset state	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

**Table 10** **GPIO\_Data\_0**

Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset state	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

**Table 11** **GPIO\_Dir\_0**

## 5.6 Reset and Sequencing

*Note: The following description assumes the maximum 150 kHz sampling frequency (Period = 5). When the sampling frequency is lower all the timings are lengthened accordingly.*

### 5.6.1 Sequencing

The interrupt signals the beginning of the sampling period. In response to the interrupt, the DSP must take the following actions:

1. Write 8 words to the DAC FIFO. To avoid a FIFO under-run the DSP has 3  $\mu$ s initially (@  $F_s = 150$  kHz) to write the first two words, then 1.6  $\mu$ s to write each remaining pair of words. This delay leaves enough margin for the FIFO write sequence to be delayed by individual reads and writes via the EMIF, or by a kernel exchange in DARAM of one complete block (256 words).
2. The DSP must then read 8 words from the ADC FIFO. The DSP has up to the next interrupt to read the ADC FIFO to avoid a FIFO overrun. The words read from the ADC FIFO have been sampled in the previous sampling period (between the previous interrupt and the present one).
3. The DSP must then read two words from the QEP counter FIFOs. The DSP has up to the next interrupt to read the counter FIFOs to avoid a FIFO overrun. The words read from the counter FIFOs have been sampled in the previous sampling period (between the previous interrupt and the present one).

### 5.6.2 Start Sequence

The recommended reset and start sequence is as follows:

1. Write to the *Control* register to reset the *Run* bit.
2. Write to the *Period* register to set the desired sampling frequency.
3. If required, prepare the DMAs to read and write the ADC, DAC and counter FIFOs in response to the sampling interrupt.
4. Write to the *Control* register to set the *Run* bit and start the sequence.

The first interrupt is triggered 80 ns (@  $F_s = 150$  kHz) after initiating the last write to the *Control* register, which deactivates the reset. Since the write itself takes more than 80 ns, this means that the first interrupt is triggered immediately after the write.

## 5.7 Bus Switches

The GPIO and QEP pins are connected to the corresponding FPGA pins on the DSP board through bus switches.

A *Presence* input is provided on J3 pin 1. This input is used to activate the bus switches that otherwise isolate all the signals of J3 from the DSP board.

The bus switches provide two functions:



- They isolate the DSP board from a user board connected on J3 when one board is powered but not the other. This is essential because in the absence of the switches, line drivers on one board could be driving un-powered input stages on the other, which could damage them.
- They provide level translation between the user-board, which can drive levels up to 5V and inputs on the DSP board, which are not 5V-tolerant. In short, the switches make the inputs 5V-tolerant.

To provide the first function, the switches should only be activated (placed in low-impedance) when the user daughter board is powered. The *Presence* input serves this purpose. This input is normally pulled-up by a 10 k $\Omega$  resistor on *SR2\_Analog\_810*, which keeps the switches open. The *Presence* pin should be pulled low by an open-drain driver on the user's daughter board, closing the switches, when the daughter board is properly powered. Pulling *Presence* low when the user's daughter board is not properly powered (before it is powered or after it is un-powered) exposes input stages on the user's board to damage inflicted by FPGA pins that may be configured as outputs. Depending on how the FPGA is configured at the time it may not be a problem. For instance if the FPGA is not configured, its IOs are floating and will not drive any current. In this case, *Presence* may be permanently tied to ground. Pulling *Presence* low when the user's daughter board is properly powered but the DSP board is not DOES NOT EXPOSE the FPGA inputs to damage that may be inflicted by line drivers on the user's daughter board. This is because the switches are open whenever the DSP board is un-powered.

The level-translation function is provided automatically whenever the switches are activated (whenever *Presence* is low).

## 6 Software

### 6.1 Demo Applications

Two demo applications are proposed, depending on the DSP board:

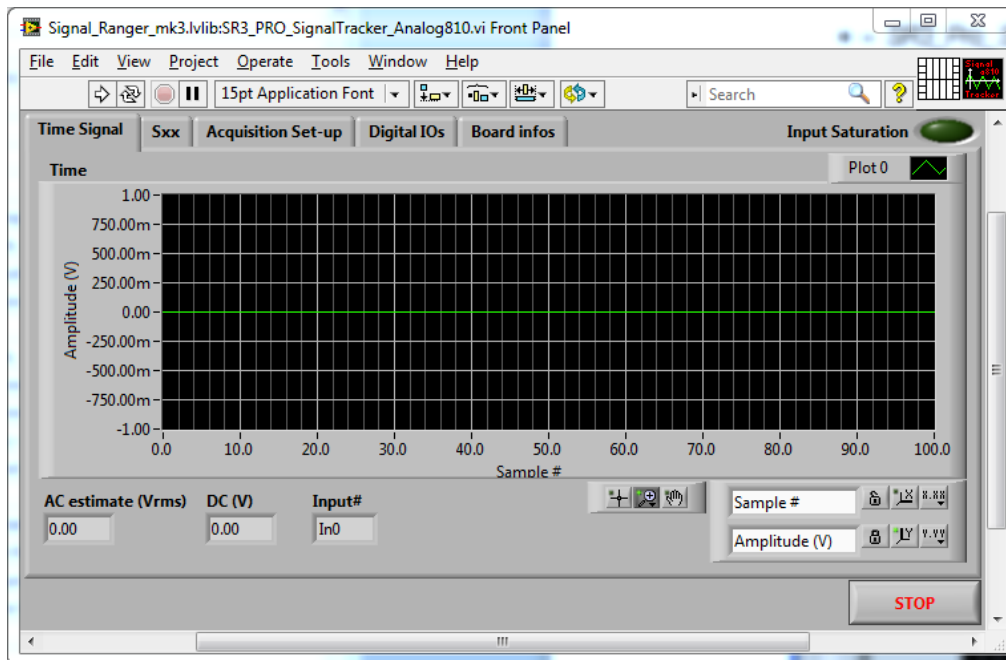
- *SR2\_NG\_SignalTracker\_Analog810* For testing using the *SR2\_NG* DSP board
- *SR3\_PRO\_SignalTracker\_Analog810* For testing using the *SR3\_PRO* DSP board

The two applications are identical, except that they are designed for the two different platforms. The two applications support *SR2\_Analog\_810\_mk1* as well as *SR2\_Analog\_810*. However, in the case of *SR2\_Analog\_810*, the TCXO clocking option is not functional and will trigger an error.

These applications have been designed to allow the test and evaluation of the analog and digital input/output channels of the *SR2\_Analog\_810\_mk1* board. The applications allow the user to send test signals to a selected output, and monitor the sampled signal on a selected input. Analog inputs are displayed both in terms of time signals, as well as instantaneous or averaged energy spectra. Averaged energy spectra are useful to assess the input noise.

The front-panel of the application is divided into several tabs, one for each functional group.





**Figure 5 SR3\_Pro\_SignalTracker\_Analog810 - Time Signal Tab**

To start the application, simply click on the white arrow at the top-left of the window.

The application sends blocks of samples of the specified length and waveform to the selected output, and records blocks of samples of the same length on the selected input. The recorded input samples are synchronous to the output samples, with a fixed and known time relationship between input and output.

## 6.1.1 Time Signal Tab

### Time Indicator

The *Time-Signal* tab presents a time plot of the signal sampled on the selected input. The amplitude scale takes into account the range of the ADC, so that the signal amplitude is represented in Volts at the connector.

### AC estimate (Vrms) Indicator

This indicator presents the RMS value of the input signal (any DC offset is removed before the RMS calculation).

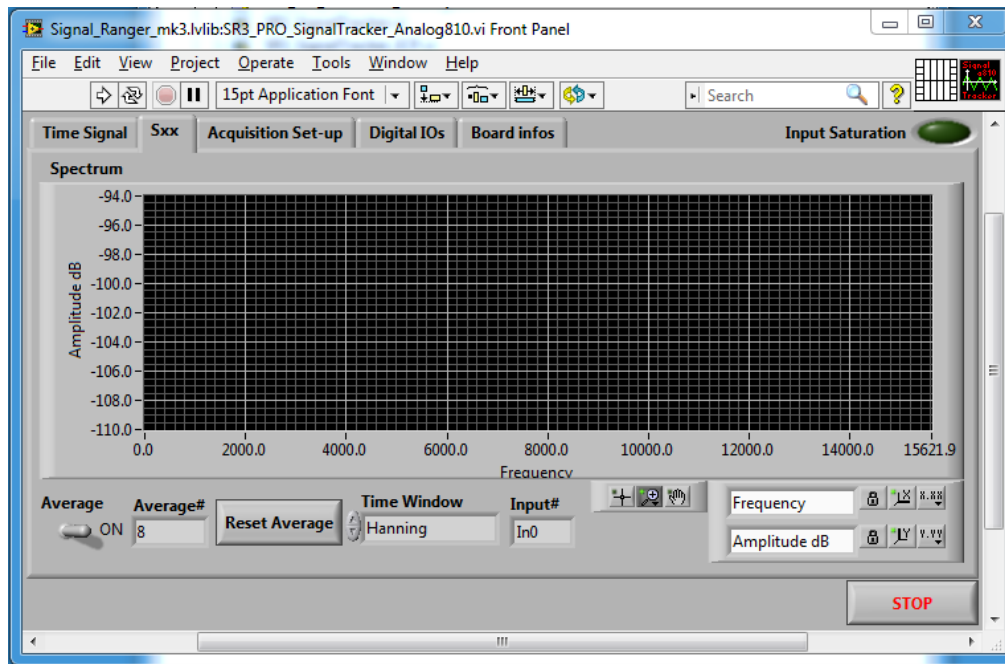
### DC (V) Indicator

This indicator presents the average DC value of the recorded time signal.

## 6.1.2 Sxx Tab

### Spectrum Indicator

The *Spectrum* indicator presents the instantaneous or averaged power spectrum of the input sampled block.



**Figure 6** SR3\_Pro\_SignalTracker\_Analog810 - Sxx Tab  
Average Control

To average the power-spectrum, simply place the *Average* control in the ON position.

### Reset Average Button

The *Reset Average* button resets the average.

### Time Window selector

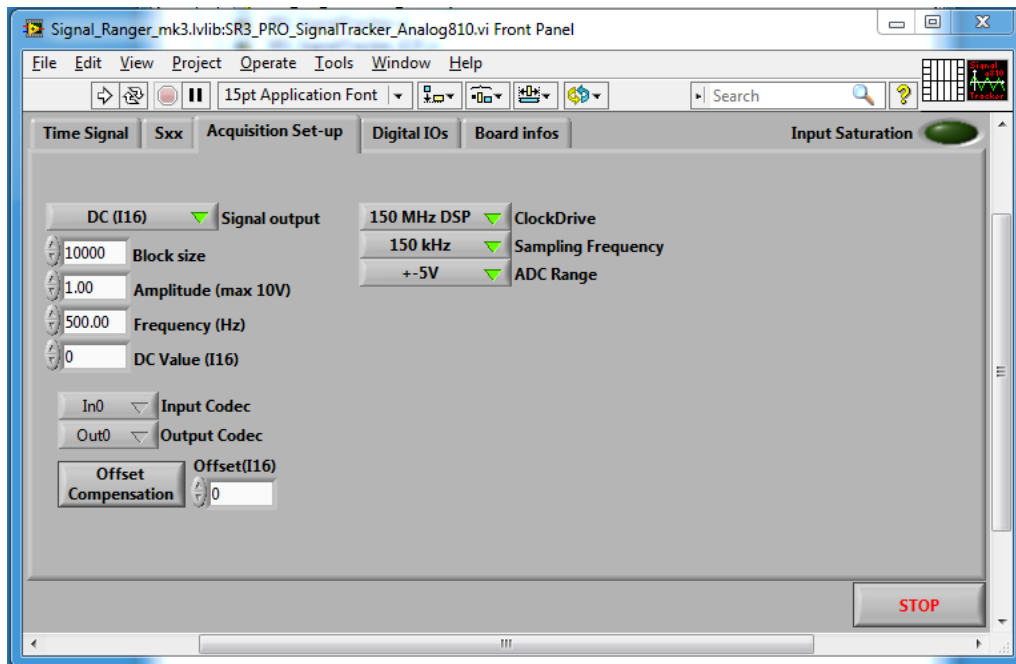
An optional weighting window can be chosen from the *Time-Window* list.

### Graph and Zoom Controls

Graph controls can be used to change the zoom factor. By default the plot is auto-scaled in X and Y, which is indicated by the closed locks beside each scale name. To disable auto-scale, simply press the lock button.

### 6.1.3 Acquisition Set-Up Tab

The *Acquisition Set-Up* tab presents the various controls for the acquisition set-up.



**Figure 7** SR3\_Pro\_SignalTracker\_Analog810 - Acquisition Tab

### Signal Output Control

The *Signal Output* control selects a type of waveform from a list of predefined waveforms. The *No Output* selection sends null samples to the output.

### Block Size Control

The *Block Size* control sets the number of samples that are sent to the output, and synchronously recorded from the input.

### Amplitude Control

The *Amplitude* control adjusts the amplitude of the output waveform. Note that the output dynamic range is  $\pm 10V$ .

### Frequency Control

The *Frequency* control is only used for periodic waveforms. It adjusts the fundamental frequency of the waveform.

### Input Codec Control

The *Input Codec* control selects the input channel between 0 and 7.

### Output Codec Control

The *Output Codec* selects the output channel between 0 and 7.

### Offset Compensation Control

The *Offset Compensation* button performs an input offset compensation. This procedure reads a block of input samples from the selected input channel while sending zero samples to the selected output

channel. The average of the input sample block is then subtracted from any further input samples. Therefore, if any offset is present on the selected input, it is subtracted in all subsequent acquisitions. The average is displayed in the *Offset(I16)* indicator. This indicator is scaled in bits. The input offset compensation is done entirely in software.

### **Offset(I16) Control**

The *Offset(I16)* indicator can also act as a control. Simply changing the content of this field forces a software offset to be applied to the recorded input samples.

### **Clock Drive Control**

The *ClockDrive* control is used to switch between the TCXO and the regular oscillator as the source of sampling frequency.

### **Sampling Frequency Control**

This control allows selecting the sampling frequency of the *SR2\_Analog\_810\_mk1* board. The list offers a limited number of selections (from 150 kHz to 25 kHz). It means that the N content of the *Period* register is limited between 5 and 30. With a simple software modification of the *SR2\_NG\_SignalTracker\_Analog810*, application the N value can be set higher than 30 (maximum 65536) to select lower sampling frequencies.

### **ADC Range Control**

This is the input range selection. Two selections are possible  $\pm 5V$  or  $\pm 10V$ .

## **6.1.4 Digital I/Os Tab**


The *Digital I/Os* tab allows the user to read or to write the digital I/Os.

### **Direction Control**

The *Direction* control selects the direction of the general-purpose I/Os (green for the read direction and red for the write direction).

### **State Control/Indicator**

The *State* control acts as an indicator for all general-purpose I/Os in read direction and as a control for all I/Os in write direction. The levels of the *State* controls are:

 : I/O at 1 (3.3 V)

 : I/O at 0 (0 V)

### **QEP\_i**

The *QEP\_0* and *QEP\_1* indicators display the contents of the 32-bit QEP/Pulse counters. The counters are augmented to 32-bits through software.

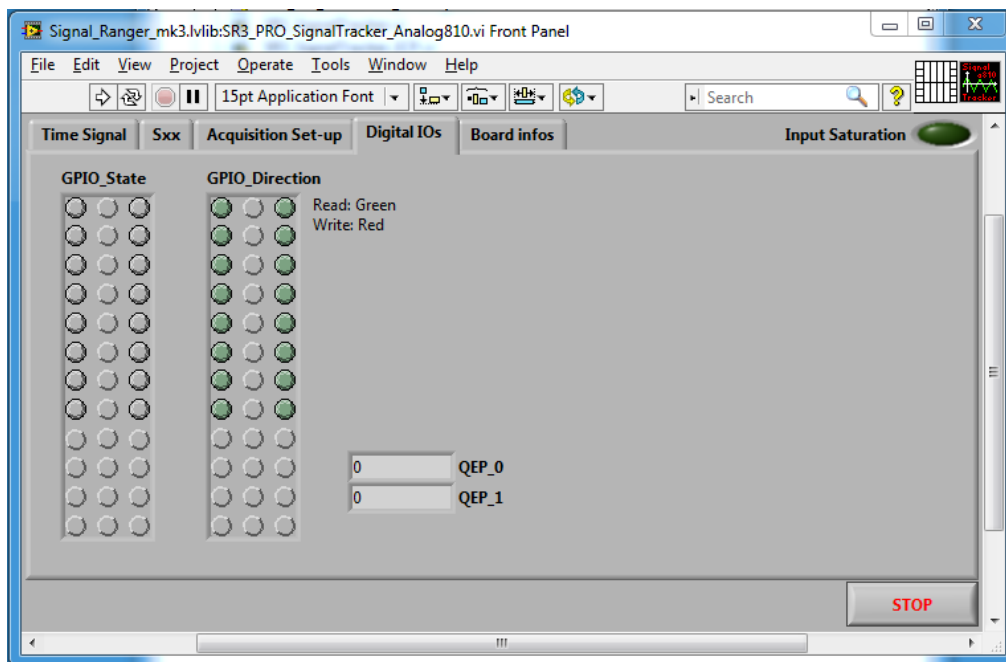


Figure 8 SR3\_Pro\_SignalTracker\_Analog810 – GPIOsTab

#### 6.1.5 Board/FPGA Info Tab

This tab presents information about the DSP board's hardware revision, Driver ID number, and FPGA configuration file.

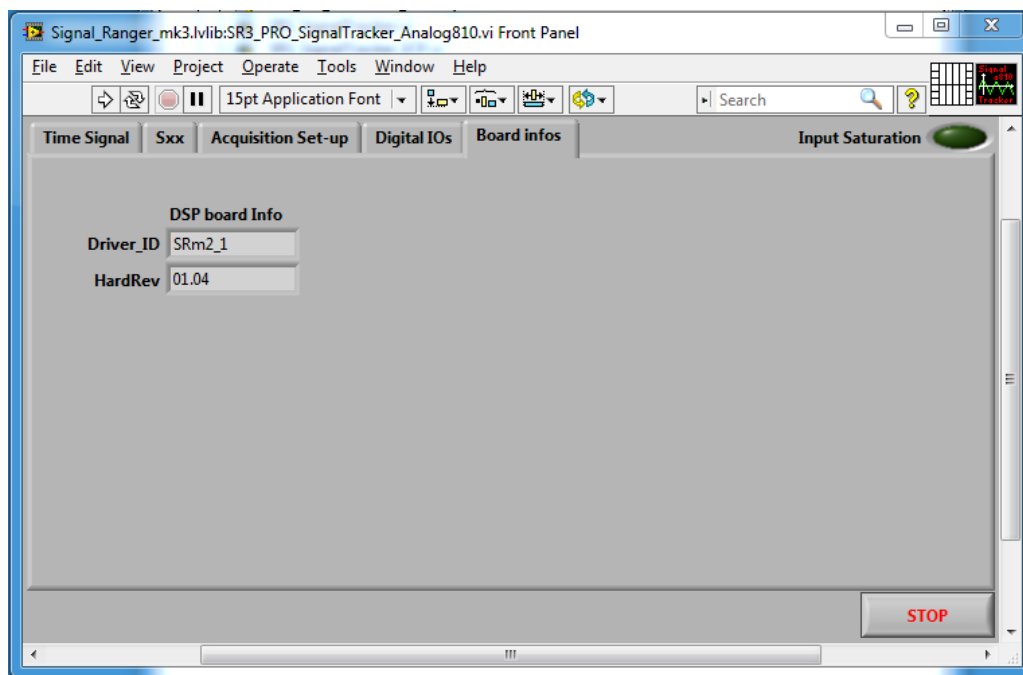


Figure 9 SR3\_Pro\_SignalTracker\_Analog810 – Board/FPGA infos Tab

## 6.2 SR2\_Analog\_810 Drivers and Example Codes

### 6.2.1 Overview

Two drivers for the analog I/Os are provided, together with the DSP code of the *Signal\_Tracker* demo applications that use these drivers. Empty shell projects are also provided for users who want to develop their own DSP application.

One driver is for the *SR2\_NG* DSP board, the other driver is for the *SR3\_Pro* DSP board.

The two drivers are identical, except where specified below.

Source code for the analog IO drivers reside in the folders named:

- *SR3PRO\_A810Driver (SignalRanger\_mk3)*.
- *SR2\_Analog810Driver (SignalRanger\_mk2\_NG)*.

Source code for the demo applications reside in the folder named:

- *SR3PRO\_A810SignalTracker (SignalRanger\_mk3)*
- *ST\_Analog810\_DSP (SignalRanger\_mk2\_NG)*.

Source code for the empty shell projects reside in the folders named:

- *SR3PRO\_A810IOShell (SignalRanger\_mk3)*
- *IO\_Shell\_Analog810 (SignalRanger\_mk2\_NG)*

The shell projects constitute excellent starting points for developing DSP code that uses the *SR2\_Analog\_810\_mk1* board.

The drivers have been optimized in assembly language, but can be used in either C, or assembly language. they take the form of DSP object libraries *sr2\_analog810driver.lib* and *SR3PRO\_A810driver.lib*. The drivers contains C-callable functions to configure and use the analog IOs. A function called *dataprocess* is provided in C, where developers can conveniently place their own analog I/O processing code.

The drivers uses the DMA to communicate with the analog IOs for maximum efficiency.

### 6.2.2 FPGA Logic

Operation of the drivers assumes that the *SR2\_Analog\_810\_TCXO\_V200.rbt* logic is loaded into the FPGA and functional. The entire logic of the module is clocked by a TCXO on the *SR2\_Analog\_810\_mk1* board. The drivers will also work with the older *SR2\_Analog\_810\_V200.rbt* logic. In that case the TCXO will not be used. Instead the regular 150 MHz *Clk\_In* signal provided by the DSP (*CLKOUT*). *CLKOUT* is provided by the DSP by default at the correct frequency. This signal is less stable than the TCXO.

### 6.2.3 User-Accessible Structures and Functions

The *sr2\_analog810driver.lib* and *sr3\_analog810driver.lib* libraries define and allocate the following user-accessible structures and variables:

#### **FreqDiv**

This unsigned short variable (16-bits) determines the sampling frequency selection. This value, between 5 and 65536, is written to the *Period* register of the FPGA logic. The maximum sampling

frequency selection is 150 kHz (N=5) and the minimum sampling frequency is 11.44 Hz (N=65535). See the section *Hardware – Period Register* for more details.

### **ADCRange**

This unsigned short variable (16-bits) selects the input range. The value 0 selects the  $\pm 10V$  range while the value 1 selects the  $\pm 5V$ . All others values are not allowed.

### **QEP\_ON**

This unsigned short variable (16-bits) indicates if the QEP counters are managed or not. Not managing the QEP counters eases the timing constraints. In particular there are two fewer FPGA reads, which can help in situations where the DSP must perform external (EMIF) accesses other than those done by the driver (see section *Restrictions* below).

- `QEP_ON = 0x0001`              QEP counters are managed
- `QEP_ON = 0x0000`              QEP counters are not managed

### **QEP\_cnt[2]**

This signed short array (16-bits) contains the contents of the two QEP counters as they are sampled by the FPGA. The contents of this array are always synchronous to the contents of the *iobuf.min* array.

### **iobuf**

This structure is designed to contain the input and output samples to/from the AICs.

The user DSP code has one complete sampling period to execute the *dataprocess* function. If the function is not completed within a sampling period input samples are overwritten by the new samples, and the previous output samples are sent to the AICs.

The structure is defined in the *Analog810Driver.h* header file.

The structure is defined as follows:

*SR2\_NG:*

```
struct iobuf_rec {  
int min[8];  
int mout[8] ;  
};
```

*SR3\_PRO:*

```
struct iobuf_rec {  
short min[8];  
short mout[8] ;  
};
```

The structure is reserved by the driver library as follows:

```
struct iobuf_rec iobuf;
```

*Note: The structure is reserved automatically as a consequence of including the driver library with the user DSP code. There is no need for the user DSP code to reserve this structure.*

*Note: All symbols must have an “\_” prefix when used from assembly code. For instance iobuf becomes \_iobuf in assembly.*

### **start\_Analog810**

This function configures the analog IOs and starts the conversion process. It has no arguments. It uses the configuration values found in the *FreqDiv*, *ADCRRange* and *QEP\_ON* variables and configures the analog IOs accordingly through the FPGA configuration registers. These variables must be initialized prior to calling *start\_Analog810*. After the execution of this function, the user-defined processing function called *dataprocess* starts being triggered at each sampling period. The LabVIEW AIC interface library includes a VI to generate the configuration variables *FreqDiv* and *ADCRRange* automatically as a function of user-selected AIC set-up.

The function is defined in the *Analog810Driver.h* (SR2\_NG) and *SR3PRO\_A810Driver.h* (SR3\_Pro) header files.

*Note: All symbols must have an “\_” prefix when used from assembly code. start\_Analog810 must be written \_start\_Analog810 in assembly.*

### **stop\_Analog810**

This function stops the AIC conversion process. After the execution of this function, the user-defined *dataprocess* function stops being triggered.

The function is defined in the *Analog810Driver.h* header file.

*Note: All symbols must have an “\_” prefix when used from assembly code. stop\_Analog810 must be written \_stop\_Analog810 in assembly.*

### **dataprocess**

This function is declared by the AIC driver library, but must be provided by the user. It usually contains the DSP code that reads the input samples from the *iobuf* structure and optionally the QEP counters, performs the signal processing between the inputs and outputs and writes the output samples to the *iobuf* structure. The *\_dataprocess* symbol must be declared using the *.global* directive when the code is written in assembler

#### **For SR2\_NG:**

Note that the *dataprocess* function is actually a TRAP.

In assembly, this function must protect all registers that it uses, and must be terminated by a RETI instruction. In C, this function must be defined with the interrupt keyword.

Just before the entry into *dataprocess*, the AIC driver enables the global interrupt mask (INTM) and the local masks INT0 and DMAC1. All other interrupts are disabled because of the time-critical nature of this function. The INT0 and DMAC1 interrupts must remain active during the execution of *dataprocess* for the driver to be functional. The local mask registers are saved on the stack and restored after the execution of *dataprocess*. If the user needs to unmask another interrupt within *dataprocess* they must be mindful of timing issues. The processing of *dataprocess* must be able to complete within one sampling period. Also all the interrupt masks are restored to their state prior to the execution of *dataprocess* at the function's exit. Therefore any interrupt enabled in *dataprocess* that was not enabled before will be disabled at exit.

#### **For SR3-Pro**



Note that the *dataprocess* function is a standard function and no special protection is required since the acquisition driver itself protects the context.

Just before the entry into *dataprocess*, the driver enables the global interrupt mask (CSR). All interrupts are disabled because of the time-critical nature of this function. The local mask registers are saved on the stack and restored after the execution of *dataprocess*. If the user needs to unmask another interrupt within *dataprocess* they must be mindful of timing issues. The processing of *dataprocess* must be able to complete within one sampling period. Also all the interrupt masks are restored to their state prior to the execution of *dataprocess* at the function's exit. Therefore any interrupt explicitly enabled in *dataprocess* that was not enabled before will be disabled at exit.

*Note: All symbols must have an “\_” prefix when used from assembly code. dataprocess must be written \_dataprocess in assembly.*

#### 6.2.4 Used Resources

The AIC driver uses the following hardware resources:

***For SR2\_NG:***

- DMA channels 0 to 1 are used by the driver.
- The DMAC0 and DMAC1 interrupts are used by the driver.
- TRAP #30 is used by the driver to launch the *dataprocess* user function.
- The external INT0 interrupt is used by the FPGA to start the DMA channel 0 and the write operations in the DAC FIFO.
- The driver uses 307 bytes of code and 18 words of data.

***For SR3-Pro:***

- DMA channels 6, 7 and 34 are used by the driver.
- Reload DMA parameters 70, 71 and 98 are used by the driver.
- The INT5 linked to DMA channel 6 is used by the driver.
- The GPIO2 signal is used by the FPGA to start the DMA channel 34 and the write operations in the DAC FIFO.
- The driver uses 1472 bytes of code and 82 bytes of data.

#### 6.2.5 Restrictions

When developing C or assembly code using the AIC driver, the following restrictions apply:

***For SR2\_NG:***

- The user-defined I/O processing function *dataprocess* must be present in the user code. If the function is defined in C, it must be defined with the *interrupt* specifier. This way, the compiler does a full context save when entering the function. If it is defined in assembly, all DSP registers used within the function must be protected upon entry, and restored upon return. It must end with the RETI instruction. The *dataprocess* symbol must be defined using the *.global* directive.
- All C-accessible symbols and labels defined in the *sr2\_analog810driver.lib* library must have a “\_” prefix when used in assembly language.
- The entire code and data sections (including .bss section) of the *sr2\_analog810driver.lib* library must be linked into the internal DARAM memory.
- The software interrupt #30, the DMAC0, the DMAC1 and the external INT0 interrupts are used by the AIC driver. The vectors for these interrupts must be properly declared. See the

*ST\_Analog810\_DSP* or the *IO\_Shell\_Analog810* DSP code projects for an example of a correct example of *vectors.asm*.

- DMA accesses to the FPGA must never be blocked for more than 2.3µs per sampling period, otherwise the driver will fail. The most obvious symptom is a shift of the ADC and DAC channel numbers.

**For SR3-Pro:**

- The user-defined I/O processing function *dataprocess* must be present in the user code. Contrary to the *SR2\_NG* case, the *dataprocess* must be a standard function. The *SR3-Pro* A810 driver does the full context save before calling the *dataprocess* function. If the function is written in assembler, the *\_dataprocess* symbol must be defined using the *.global* directive.
- All C-accessible symbols and labels defined in the *SR3PRO\_A810Driver.lib* library must have a “\_” prefix when used in assembly language.
- The INT5 linked to the DMA channel 6, the GPIO2, the DMAC channels 6, 7, 34, 70, 71 and 98 are used by the AIC driver. The vectors for these interrupts must be properly declared. See the *SR3PRO\_A810SignalTracker* or the *SR3PRO\_A810IOShell* DSP code projects for an example of a correct implementation of *vectors.asm*.
- DMA accesses to the FPGA must never be blocked for more than 2.3µs per sampling period, otherwise the driver will fail. The most obvious symptom is a shift of the ADC and DAC channel numbers.

#### 6.2.6 Driver Lock-Up

##### *SR2\_NG Only*

Because the driver relies on the DMA for writing and reading in the ADC and DAC FIFOs, there are situations that can lead to a lock-up. The DARAM can only support 2 accesses per DSP cycle, for which the CPU always has priority against DMA and HPI accesses. Some rare sequences of instructions, when executed in a tight loop require those two DARAM accesses per cycle, thereby completely denying access to the DMA. This condition occurs only when the code is executing from the same DARAM block where the DMA buffer resides. Under these conditions the DMA transfers never complete. Therefore the interrupt #30 is never triggered and the *dataprocess* user function is never called. This situation may be accompanied by a USB lock-up if the code executes from the first DARAM block, because the HPI uses the DMA for transfers and is subject to the same priority rules (see *Signal\_Ranger\_mk2\_UserManual.pdf*).

There are several workarounds that can be applied:

- The DMA section (named *dmabuf* in the AIC driver) may be moved to a DARAM block other from the block containing the offending code loop.
- The offending code loop may be modified to avoid requiring two accesses per cycle. A simple fix is usually to insert NOP instructions in the loop. The situation is very rare so most code reorganizations will usually fix the problem.